

Programming framework for cognitive agents

(motivation & overview)

Peter Novák

Computational Intelligence Group IfI @ TUC

February 22, 2007

Peter Novák · Computational Intelligence Group Ifl @ TUC

February 22, 2007 1/16



Outline

1 Motivation

- Scenarios
- Problem
- 2 State of the art
- 3 Jazyk project
 - Modular BDI architecture
 - Jazyk: The language
 - Higher level programming constructs
 - Discussion
- 4 Conclusion



Motivation scenarios (Robot contests)

RoboCup Rescue League

- team of agents navigating in a fairly complex map
- several types of agents
- limited communication resources

RoboCup Four-Legged League

2 teams of 4 robots playing soccer

AAAI Robot competition: Integration challenge

Integrate existing components to produce a working robot that is: robust, fault-tolerant, flexible, easily adaptable to new tasks



Motivation scenarios (Robot contests)

RoboCup Rescue League

- team of agents navigating in a fairly complex map
- several types of agents
- limited communication resources

RoboCup Four-Legged League

2 teams of 4 robots playing soccer

AAAI Robot competition: Integration challenge

Integrate existing components to produce a working robot that is:

robust, fault-tolerant, flexible, easily adaptable to new tasks



Motivation scenarios (Robot contests)

RoboCup Rescue League

- team of agents navigating in a fairly complex map
- several types of agents
- limited communication resources

RoboCup Four-Legged League

2 teams of 4 robots playing soccer

AAAI Robot competition: Integration challenge

Integrate existing components to produce a working robot that is:

robust, fault-tolerant, flexible, easily adaptable to new tasks



Knowledge manipulating autonomous agents

Agent (working definition)

Software entitity *embodied* in an environment, which acts *autonomously* and proactively in order to reach its *goals*.

Agent with mental states

- builds a model of its environment
- explicitely uses *mental attitudes* ~~ keeps track of goals, its decisions and contexts it is currently in

----> Hybrid cognitive robotic architectures: e.g. BDI.



Knowledge manipulating autonomous agents

Agent (working definition)

Software entitity *embodied* in an environment, which acts *autonomously* and proactively in order to reach its *goals*.

Agent with mental states

- builds a model of its environment
- explicitely uses *mental attitudes* ~~> keeps track of goals, its decisions and contexts it is currently in

----> Hybrid cognitive robotic architectures: e.g. BDI.



Challenges

- 1 reactiveness vs. mental states (deliberation)
- 2 knowledge representation modularity

Problem

Develop a BDI based programming system for development of agents with mental states:

- architecture
- programming language
- methodology



State of the art

BDI based programming systems

Engineering approaches (JACK, Jadex)

- layer of specialized constructs over Java → easy code re-use, vast number of 3rd party libraries
- easy integration with external systems/environment
- semantics of the underlying programming language
- knowledge representation in terms of an imperative/object language

Theoretically driven (AgentSpeak(L), 3APL)

- declarative programming language built from scratch ~~> new syntax
- no direct integration with 3rd party/legacy systems
- clear theoretical properties ~>> easier verification(?)
- declarative KR techniques (currently rather weak reasoning capabilities)



Modular BDI architecture

Knowledge Representation:

- encapsulate BDI modules allowing only *query/update* interface
- KR techniques and programming languages ~~ programmer's decision
- treat agent's capabilities as just another BDI component

Agent System Dynamics:

interaction between BDI modules ------ interaction rules

application of a interaction rule ---- atomic system transition

Interpreter:

select and execute arbitrary applicable interaction rule



Modular BDI architecture

Knowledge Representation:

- encapsulate BDI modules allowing only *query/update* interface
- KR techniques and programming languages ~~ programmer's decision
- treat agent's capabilities as just another BDI component

Agent System Dynamics:

- application of a interaction rule ~~> atomic system transition

Interpreter:

select and execute arbitrary applicable interaction rule



Modular BDI architecture

Knowledge Representation:

- encapsulate BDI modules allowing only *query/update* interface
- KR techniques and programming languages ~~ programmer's decision
- treat agent's capabilities as just another BDI component

Agent System Dynamics:

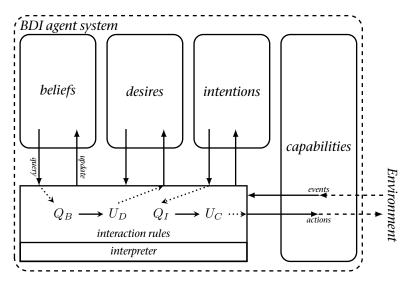
- application of a interaction rule ~~> atomic system transition

Interpreter:

select and execute arbitrary applicable interaction rule



Architecture





Example: Espresso machine

Beliefs (Prolog)	Desires (set of Prolog atoms)
ready :- cup_present, cup_empty, not error.	make_espresso.
	Capabilities (C)
Intentions (stack - Lisp)	
(define push) (define pop) (define top?)	<pre>void mill_start(); void mill_stop(); int stand_empty(); int cup_empty();</pre>

 $Q_C(\text{!stand_empty()} \& cup_empty()) \longrightarrow U_B(\text{assert(cup_present)})$

 $Q_B(\mathsf{ready}) \wedge Q_D(\mathsf{make_espresso}) \longrightarrow U_I((\mathsf{push}\ (\mathsf{grind}\ \mathsf{boil}\ \mathsf{pour}\ \mathsf{clean})))$

 $Q_I((top? grind)) \longrightarrow U_C(mill_start()) \circ U_I((pop))$

Peter Novák · Computational Intelligence Group Ifl @ TUC

February 22, 2007 9/16



Example: Espresso machine

Beliefs (Prolog)	Desires (set of Prolog atoms)
ready :- cup_present, cup_empty, not error.	make_espresso .
Intentions (stack - Lisp)	Capabilities (C)
(define push) (define pop) (define top?)	<pre>void mill_start(); void mill_stop(); int stand_empty(); int cup_empty();</pre>

 $Q_C(\text{!stand_empty()} \& cup_empty()) \longrightarrow U_B(\text{assert(cup_present)})$

 $Q_B(\text{ready}) \land Q_D(\text{make}_\text{espresso}) \longrightarrow U_I((\text{push}(\text{grind boil pour clean})))$

 $Q_I((\text{top? grind})) \longrightarrow U_C(\text{mill_start()}) \circ U_I((\text{pop}))$

Peter Novák · Computational Intelligence Group Ifl @ TUC

February 22, 2007 9/16



Programming language: syntax

declare beliefs as Prolog [{ ... }] declare desires as Prolog [{ ... }] declare intentions as Lisp [{ ... }] declare capabilities as C [{ ... }]

when query capabilities [{!stand_empty}]
 then update beliefs [{assert(cup_present)}];

when query beliefs [{ready}] and query desires [{make_espresso}]
 then update intentions [{(push (...))}];

when query intentions [{(top? grind)}]
 then update capabilities [{mill_start()}], update intentions [{(pop)}];

when query desires(Type) [{make(Type)}] and query beliefs [{ready}]and query beliefs(Type,Time,Temp,Vol) [{recipe(Type,Time,Temp,Vol)}] then update intentions(Type,Time,Temp,Vol) [{(push ((grind Time)(boil Temp)(pour Vol)(done Type)))}];

Peter Novák · Computational Intelligence Group Ifl @ TUC

February 22, 2007 10/16



Programming language: syntax

declare beliefs as Prolog [{ ... }] declare desires as Prolog [{ ... }] declare intentions as Lisp [{ ... }] declare capabilities as C [{ ... }]

when query capabilities [{!stand_empty}]
 then update beliefs [{assert(cup_present)}];

when query beliefs [{ready}] and query desires [{make_espresso}]
 then update intentions [{(push (...))}];

when query intentions [{(top? grind)}]
 then update capabilities [{mill_start()}], update intentions [{(pop)}];

when query desires(Type) [{make(Type)}] and query beliefs [{ready}]and query beliefs(Type,Time,Temp,Vol) [{recipe(Type,Time,Temp,Vol)}] then update intentions(Type,Time,Temp,Vol) [{(push ((grind Time)(boil Temp)(pour Vol)(done Type)))}];



Mental state transformers

Observations

- rule (a set of rules) ~>> partial function on the set of mental states
- unification of two sets of rules ~~> partial function! generalization
- nested rules ~~> partial function again! specialization

... named compound code structures? ---- add macro expansion facility!



Mental state transformers

Observations

- rule (a set of rules) ~>> partial function on the set of mental states
- unification of two sets of rules ~~> partial function! generalization
- nested rules ~~> partial function again! specialization

 $\ldots\,$ named compound code structures? \leadsto add macro expansion facility!



Example: Stock exchange trading agent

define careful_strategy(TITLE) {

when [{ wants(TITLE) }] then [{ drop_goal(wants(TITLE)) }];

define opportunistic_strategy(TITLE) {

when [{ wants(TITLE) }] and [{ price(TITLE)<avg(TITLE,12h) }]
then [{ act(issue_order(buy(TTILE,10))) }];</pre>

when [{ price(TITLE)<max(TITLE,180d) }] and [{ price(TITLE)<avg(TITLE,7d) }]
then [{ introduce_goal(wants(TITLE)) }];</pre>

defineq market_turmoil {

```
[{ news('overtake')>2 }] and [{ avg(DOW,5h)<0.70*avg(DOW,2d) }]
```

```
when market_turmoil then {
```

```
careful_strategy(APPL);
careful_strategy(MSFT);
```

} else {

```
opportunistic_strategy(APPL);
opportunistic_strategy(MSFT);
```



Pros and cons

Pro's:

- translational semantics ~~> plain program
- source code modularity ~~> behaviors(?)
- integration of heterogenous components under a BDI umbrella

That's all nice, but:

- how to use it?
- mst's vs. behaviors, roles, etc.
- mst's vs. BDI concepts (goal directed decomposition)
- methodology:
 - how to decompose a problem into mst's?



Pros and cons

Pro's:

- translational semantics ~~> plain program
- source code modularity ~~> behaviors(?)
- integration of heterogenous components under a BDI umbrella

That's all nice, but:

- how to use it?
- mst's vs. behaviors, roles, etc.
- mst's vs. BDI concepts (goal directed decomposition)
- methodology:
 - how to decompose a problem into mst's?



Ongoing work and outlooks

Modular BDI architecture

paper published, AAMAS 2006.

Programming language

- code modularity ~~> higher level programming constructs (mental state transformers), TR IfI-06-12
- Jazyk language interpreter under construction (summer 2007?)

Methodology

experiments, experiments, experiments! ---- bottom-up approach

Peter Novák · Computational Intelligence Group Ifl @ TUC

February 22, 2007 14/16



Ongoing work and outlooks

Modular BDI architecture

paper published, AAMAS 2006.

Programming language

- code modularity ~~> higher level programming constructs (mental state transformers), TR IfI-06-12
- Jazyk language interpreter under construction (summer 2007?)

Methodology

experiments, experiments! ---- bottom-up approach



Conclusion

Project

Programming framework for development of BDI agents with mental states:

- architecture
- programming language
- methodology

Modularity & integration

Different programming languages are suitable for different knowledge representation tasks.



Conclusion

Question?

THANK YOU FOR YOUR ATTENTION.

Peter Novák · Computational Intelligence Group Ifl @ TUC

February 22, 2007 16/16